

欢迎来到机器人的世界

主讲人:田博

Tianbot 创始人

机器人:国际现状









Google Boston Dynamics 大疆 Matrice 100









Fetch Robotics-Fetch/Freight NXROBO-BIG i

Willow Garage-PR2

Rethink Robotics-Baxter

机器人:国内现状







李克强总理感受百度机器人小度



优必选机器人登上央视春晚



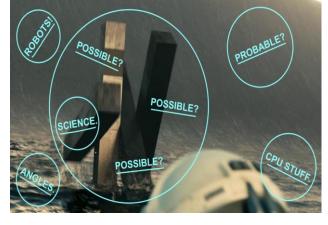
科沃斯扫地机器人改变家庭清洁方式

科幻故事中的机器人发展





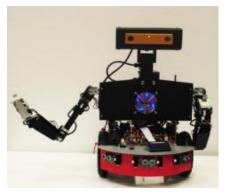




我的机器人研发经历











面向商业的服务机器人









移动巡检 接待引导









机器人发展趋势

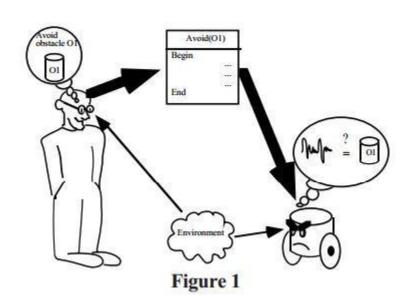
规划和控制

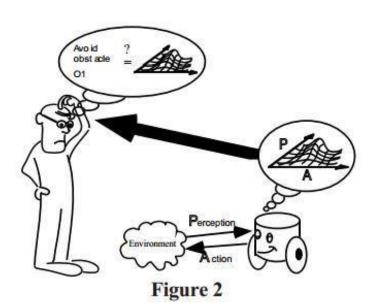
移动性能

适应性 与空间认知

理解力 与安全性

物质决定谁的意识?







It begins with the birth of a new people, and the choices they will have to make, and the people they will decide to become.



Re-Inventing the Wheel

First, someone publishes...



...and they write code that barely works but lets them publish...



...a paper with a proof-ofconcept robot.



This prompts another lab to try to build on this result...



But inevitably, time runs out...



...but they can't get any details on the software used to make it work...



...and countless sleepless nights are spent writing code from scratch.



Son a grandiose plan is formed to write a new software API...



...and all the code used by previous lab embers is a mess.

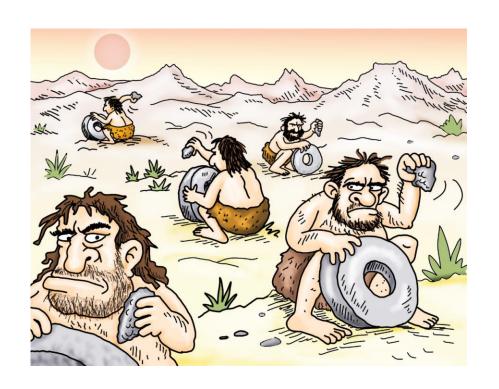
多学科——软件、机械、电子、算法...

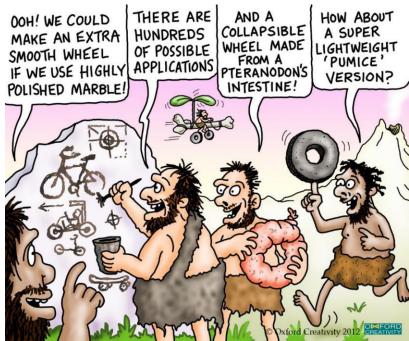
软硬件不是即插即用(驱动、接口)

缺乏统一标准,难以整合已有成果和资源

缺乏功能库和开发工具

重复造轮子?











ROS Kinetic Kame Kinetic Kame is the 10th official ROS release. It is supported on Ubuntu Wily ROS Spotlight: ROS Lunar Loggerhead Tshirts Available!





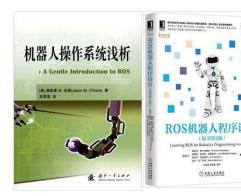


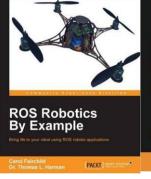




如何学ROS?











IIROS Robots







































国际知名企业机器人企业以ROS作为机器人研发首选

Nvidia、博世、高通、英特尔、宝马、大疆等 国内外各大公司纷纷推出ROS接口



入道在这里 知乎个人主页: 贾子枫



入行在这里 天之博特公众号

我们的公开讲座



如何玩转 ROS 机器人程序设计 贾子枫, Top Liu

科学技术 ★★★★★ 305 人参与



畅谈 SLAM 即时定位建图技术 贾子枫, 半闲居士

科学技术 ★★★★★ 503 人参与



机器人技术的行业发展与创业方向 贾子枫

科学技术 ★★★★★ 625 人参与









谢谢大家