

机器人操作系统及其应用

2016暑期学校

2016.7.22~7.28

智能机器人运动与视觉实验室

华东师范大学(中山北路校区)

第三天(2016年7月24日),地点:理科楼B222

主题: ROS机器人开发框架基础

时间	题目	报告人
9:00 AM 9:15 AM	署期学校讲者介绍	张新宇
9:15 AM 10:45 AM	ROS基础 驭象智能科技(上海) 华东师范大学	符国和,CTO
10:45 AM 11:00 AM	茶歇休息15分钟	
11:00 AM 12:30 PM	ROS基础 驭象智能科技(上海) 华东师范大学	符国和,CTO
	午餐 企业产品展	
13:30 PM 15:00 PM	Basic ROS(in English) 上海科技大学机器人实验室	Sören Schwertfeger
15:00 PM 15:15 PM	茶歇交流活动	
15:15 PM 17:45 PM	Basic ROS(in English) 上海科技大学机器人实验室	Sören Schwertfeger

就餐

河西食堂:二楼可现金

韩国餐厅:二楼可现金

可以借周边同学校园卡

无线网络热点

ECNU: 需要打开浏览器 根据提示输入WEB账号/密码

下面两个热点无需密码ROSSUMMERSCHOOL_1ROSSUMMERSCHOOL_2

机器人操作系统(ROS) 暑期学校公众号



ROS基金会淘宝二维码







讲者介绍

2016年7月24日





符国和

驭象智能科技有限公司, CTO

2013年本科毕业于电子科技大学。

2016年毕业于华东师范大学"智能机器人运动与视觉实验室"。

现为驭象智能科技(上海)有限公司CTO。

2012年获取全国大学生电子设计竞赛——

"Intel"杯嵌入式邀请赛二等奖,作品为垃圾分类机器人。

2015年参加Intel RealSense大赛,进入决赛,作品为基于ROS的社交机器人。申请发明专利5项。



Sören Schwertfeger

He received his Diploma (German equivalent of the Master) in Computer Science in 2005 from the University of Bremen in Germany. In 2012 he received his Ph.D. in Computer Science from the Jacobs University Bremen, Germany. Between 2012 and 2014 he was a postdoctoral researcher at the Robotics Group of Prof. Andreas Birk at the Jacobs University Bremen. In 2010 Dr. Schwertfeger was a guest researcher at the National Institute of Standards and Technology (NIST) in Gaithersburg, Maryland, USA, where he did research on robot performance evaluation and map quality assessment. In 2015 he also was a guest researcher at UC Berkeley. His research interest is in robotics, especially in intelligent functions for mobile robots. Besides his work on map evaluation, Dr. Schwertfeger also worked and published on mapping, object detection and robot autonomy. He successfully participated in many robot competitions, both as team member and as judge and organizer. Dr. Schwertfeger was the chair of the 2014 German Open RoboCup Rescue competition. In 2011 he won the best paper award at the International Workshop on Safety, Security, and Rescue Robotics (SSRR).

